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Abstract of the Disclosure

OPERATOR INTERFACE SYSTEM

In the operation of work machines it has been a problem to control the work machine's velocity aspects such as velocity, acceleration, deceleration and jerk because of the plurality of operator interfaces required for such control. The present invention provides an operator interface system for a work machine in which a first pedal is displaceable from a neutral position, and a sensor is operatively coupled with the first pedal and is operable to output a displacement signal corresponding to a location of the first pedal. An electronic controller receives the displacement signal and provides a pre-determined control to a velocity aspect of the work machine in response to the displacement signal.

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